

POLARIS

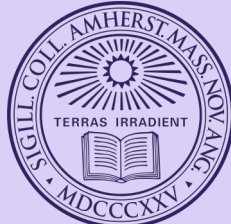
Sampling from the Multigraph Configuration Model with Prescribed Color Assortativity

Giulia Preti
(CENTAI)

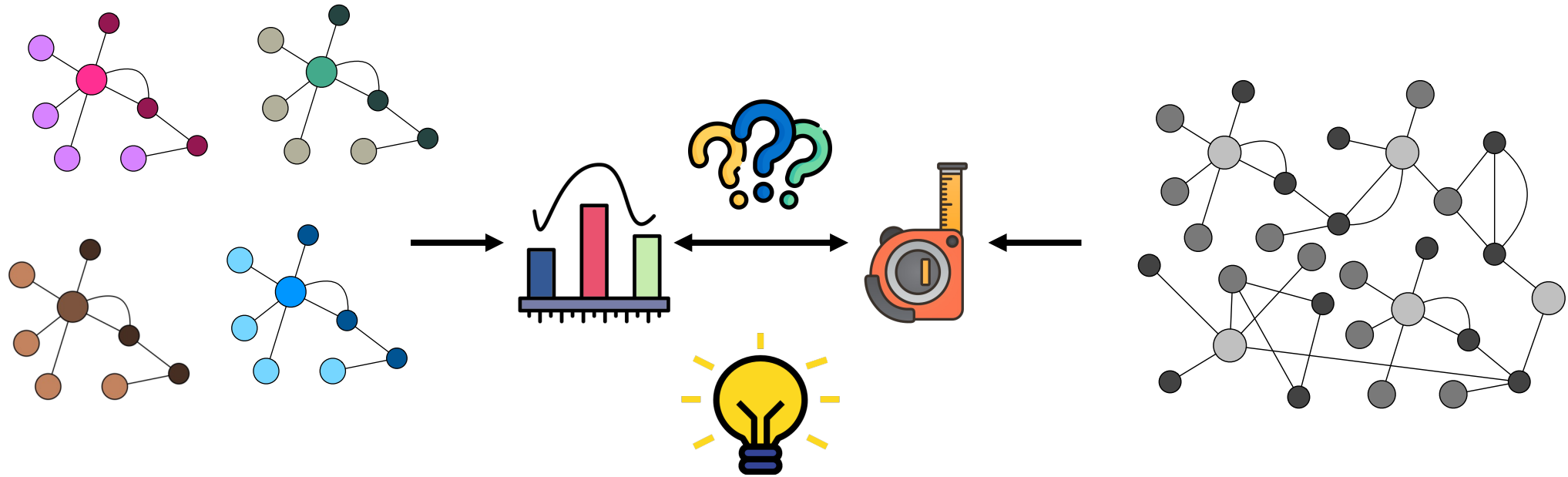
Matteo Riondato
(Amherst College)

Aristides Gionis
(KTH)

Gianmarco De Francisci
Morales (CENTAI)



Why Graph Null Models?



we can assess
statistical significance!

What is a Null Model?

P

“some” properties of the
observed structure

Z

structures satisfying those
properties but **otw random**
(**ensemble**)

(Z, π)

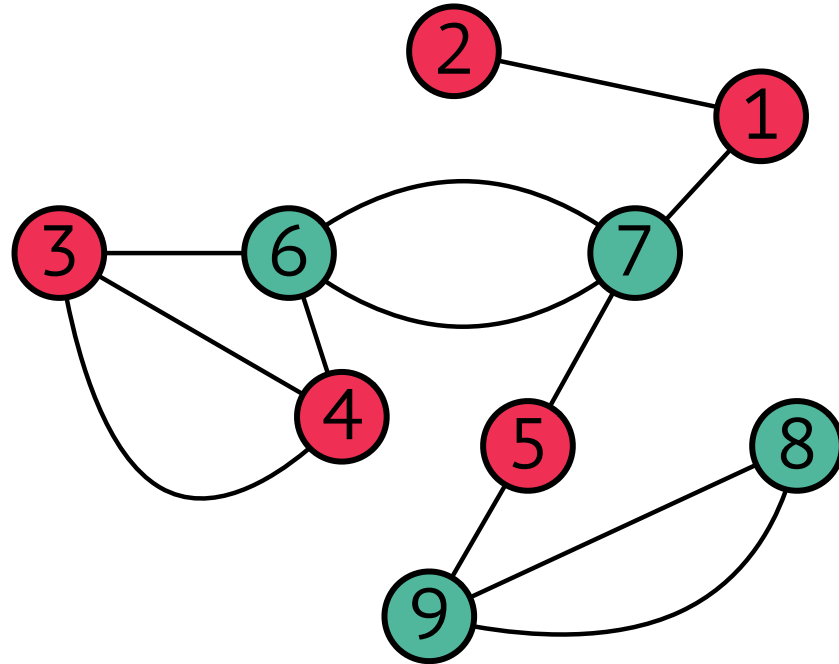
null model

π is a probability
distribution over Z

How did we **define P** ?

How did we **efficiently draw** from Z according to π ?

Undirected Colored Multigraphs



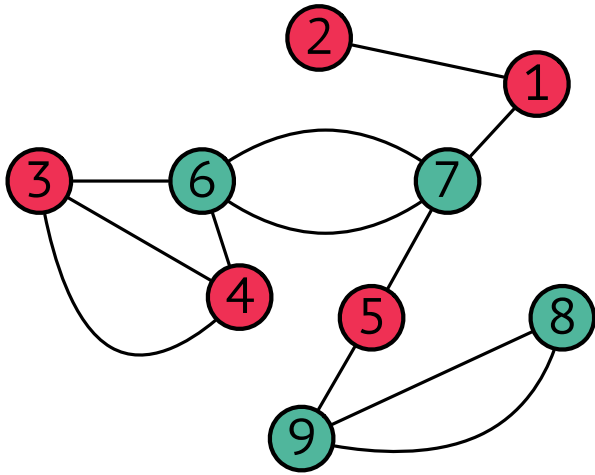
Nodes are colored

The edgeset is a multiset

Can model social networks

Example: Congress bill co-sponsorship network where colors are political parties

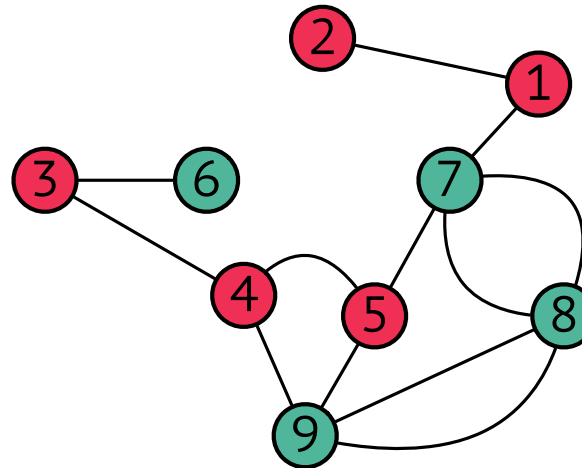
Joint Color Matrix (JCM)



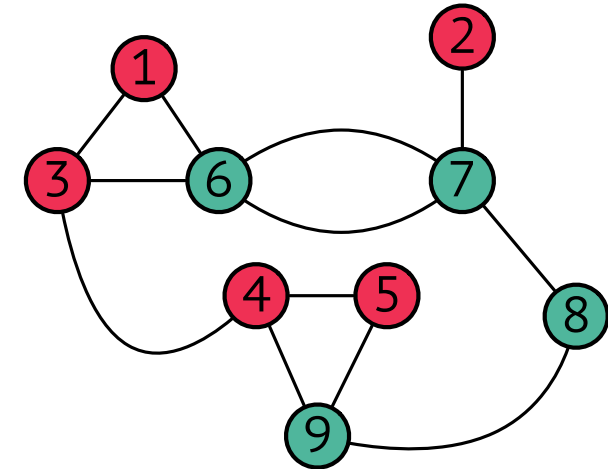
degrees: [2,1,3,3,2,4,4,2,3]
color assortativity: 0.161

JCM preserves the
color assortativity

	3	5
5		4



degrees: [2,1,2,3,3,1,4,4,4]
color assortativity: 0.161



degrees: [2,1,3,3,2,4,4,2,3]
color assortativity: 0.161

JCM does not preserve
the node degrees

Types of Ensembles

Canonical: constraints are satisfied on expectation

Micro-canonical: constraints are enforced exactly

How to sample from Micro-canonical ensembles?

Markov Chain Monte Carlo

Markov Chain Monte Carlo (MCMC)

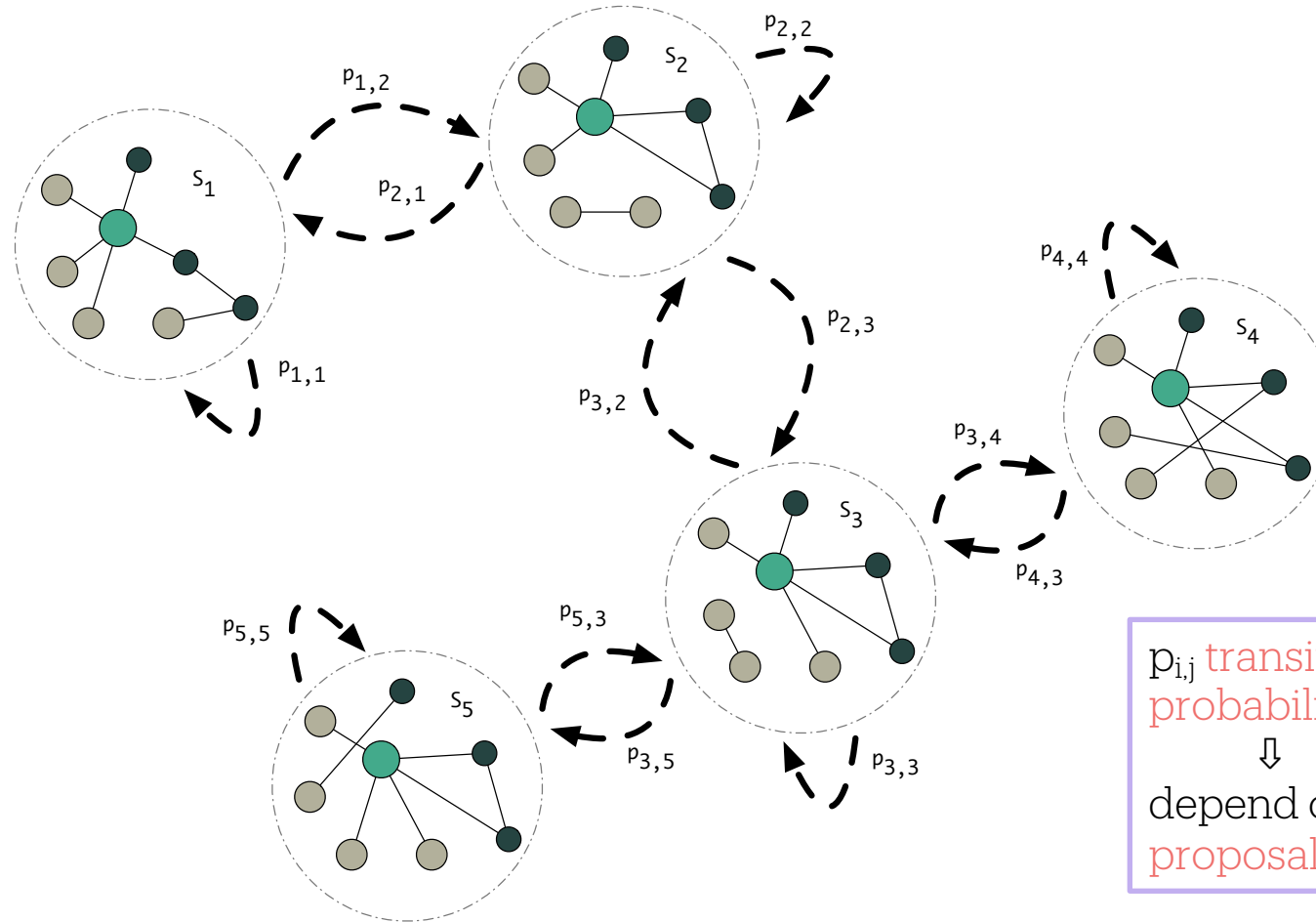
Markov Graph
(MG) strongly
connected and
aperiodic



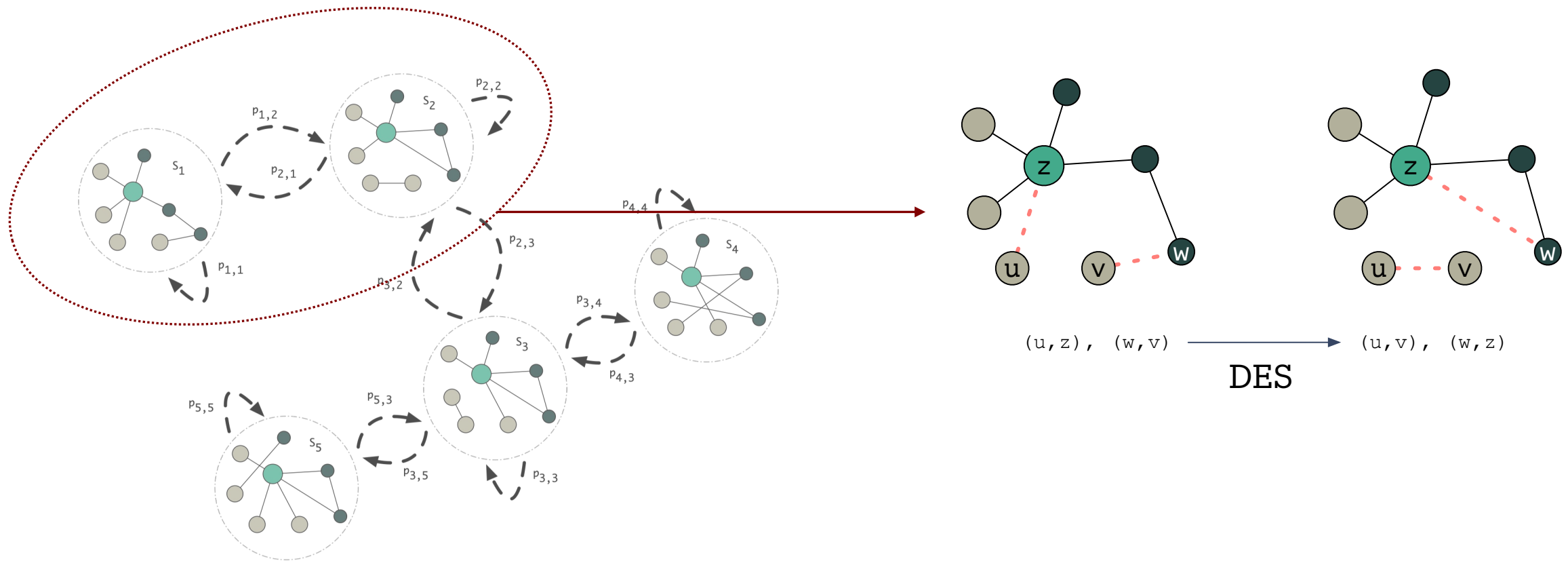
Markov Chain
(MC) is **ergodic**



MC eventually
samples from Z
with dist. π



Double Edge Swaps (DESs)




Metropolis Hastings (MH)

MH randomly **attempts to move** onto the MG

Sometimes it accepts the move,
and **sometimes it rejects** it

Acceptance **depends on the current state**

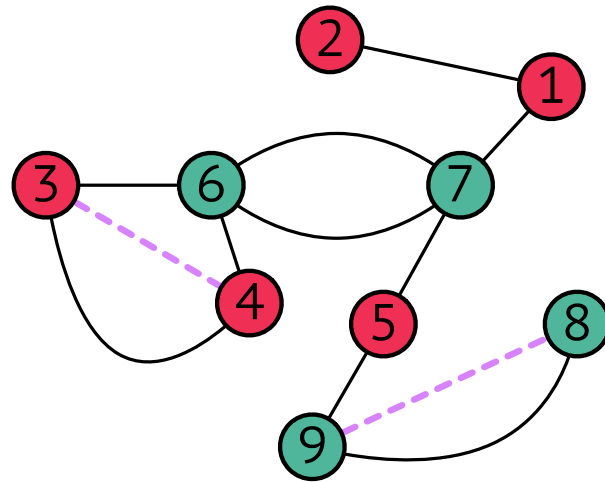
$$\alpha_v(u) = \min \left\{ 1, \frac{\pi(u)}{\pi(v)} \frac{\xi_u(v)}{\xi_v(u)} \right\}$$


neighbor
proposal
probability

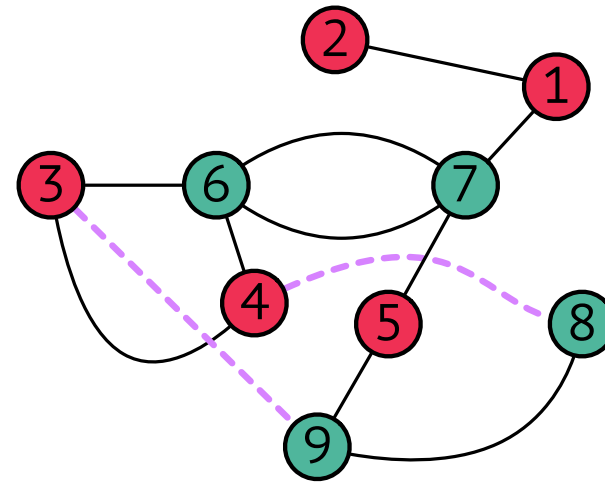
A Color-agnostic Algorithm: Polaris-B

We adapted an algorithm for **uncolored** multigraphs

Since it operates via DESs, it must **stay in the current state** if the sampled **DES changes the JCM**



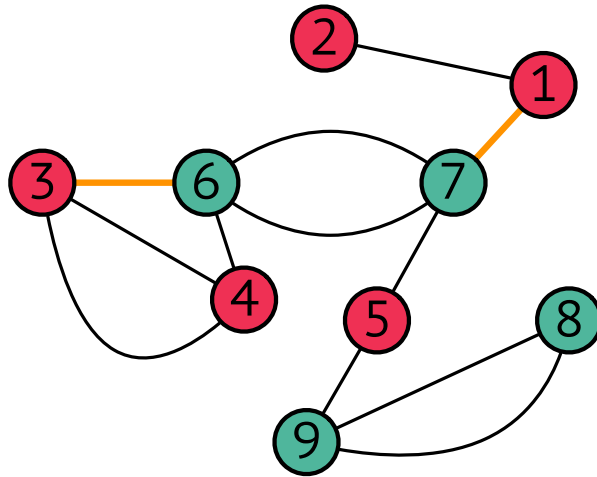
DES



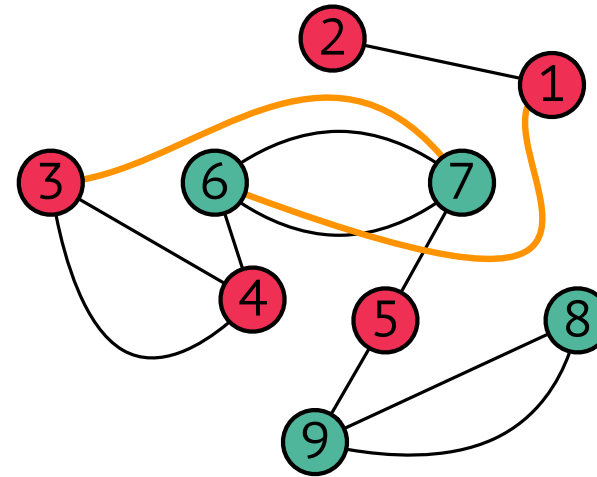
JCM-preserving Double Edge Swap (JDESs)

A JDES is a DES where the sources and/or the destinations of the edges have the same color.

This ensures that the JCM is preserved.



JDES

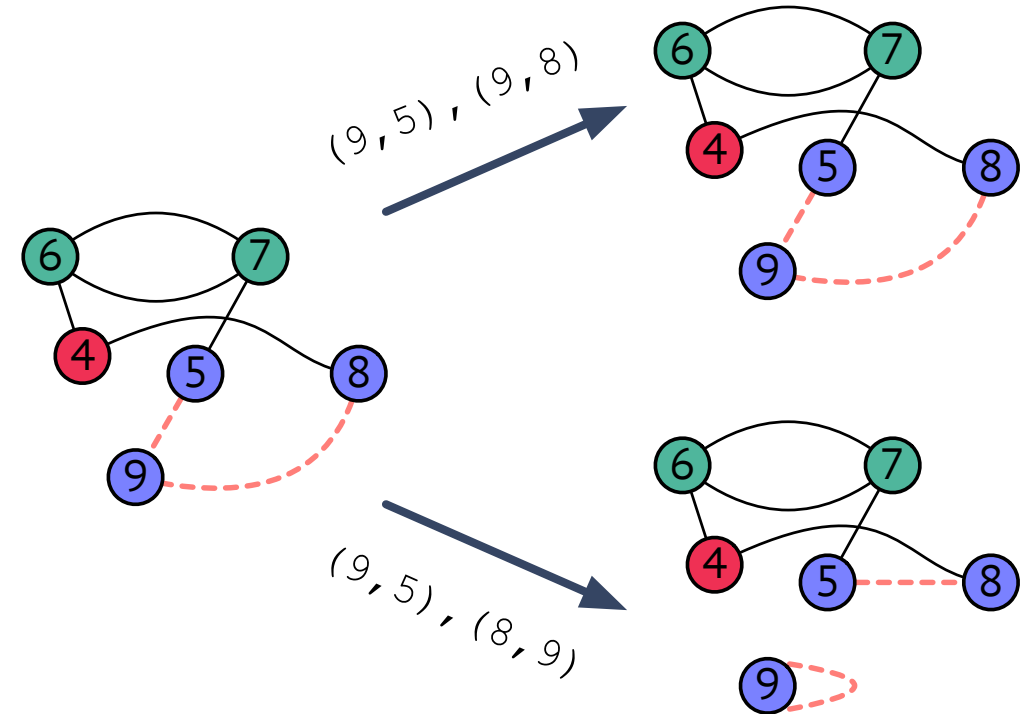


A Color-aware Algorithm: Polaris-C

Polaris-C **avoids** sampling pairs of edges such that **neither is a JDES**

If one of the JDESs does not change the current state (no-op), it **chooses the other one (moving)**

Polaris-C **reduces the probability** that the MC **stays in the current state**



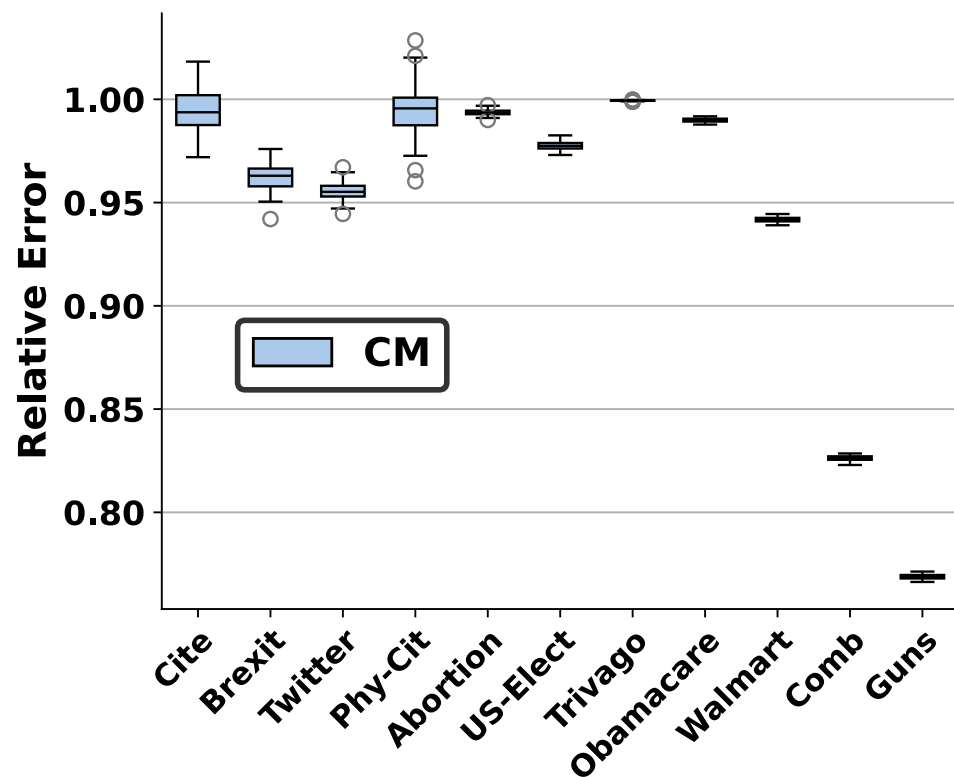
For **undirected unipartite** graphs,
two DESs for each pair of edges!

DES Characterization

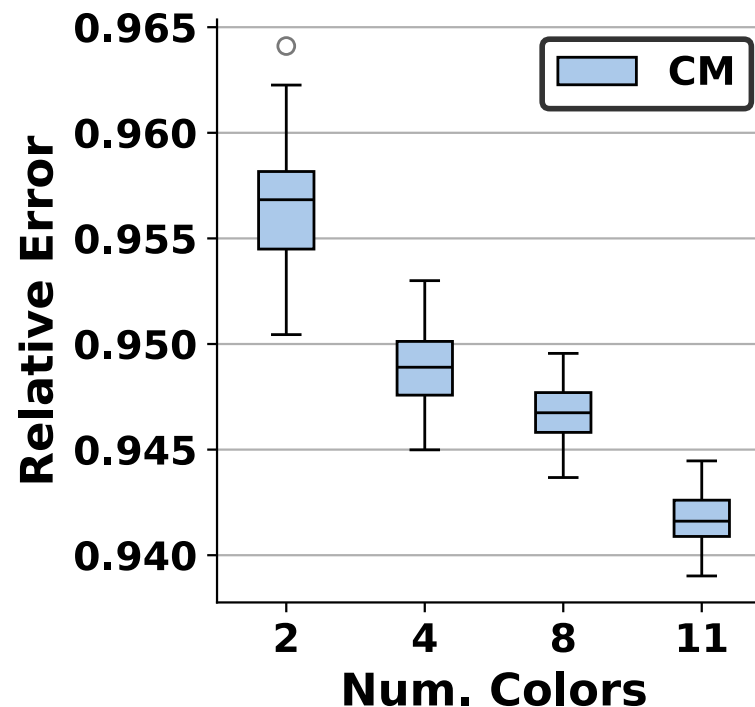
0			3b		1 moving JDES 1 no-op JDES
1		2 no-op JDESs	3c		1 moving JDES 1 no-op JDES
2a		2 moving JDESs	3d		1 no-op JDES
2b		1 moving JDES 1 no-op JDES	3e		1 no-op JDES
2c		1 no-op JDES	4a		1 moving JDES
2d		2 no-op JDESs	4b		1 moving JDES
3a		2 moving JDESs	4c		2 moving JDESs

Comparison with the Configuration Model

CM: a graph is chosen u.a.r. from the collection of all graphs with given degree sequence

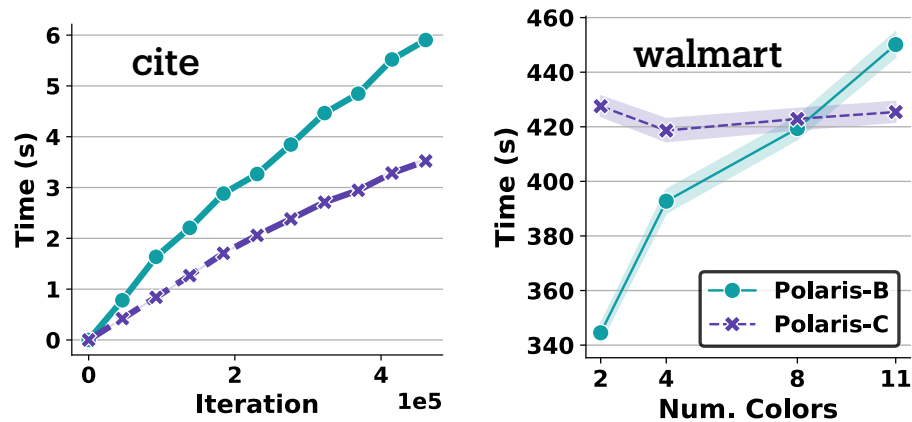


CM does not preserve color assortativity

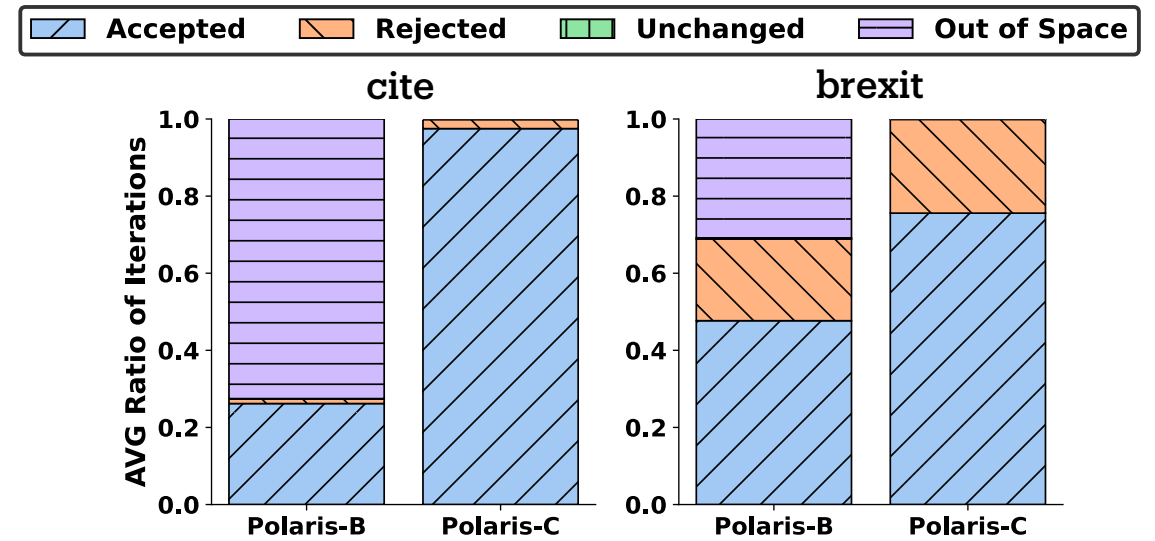


error decreases with the number of colors

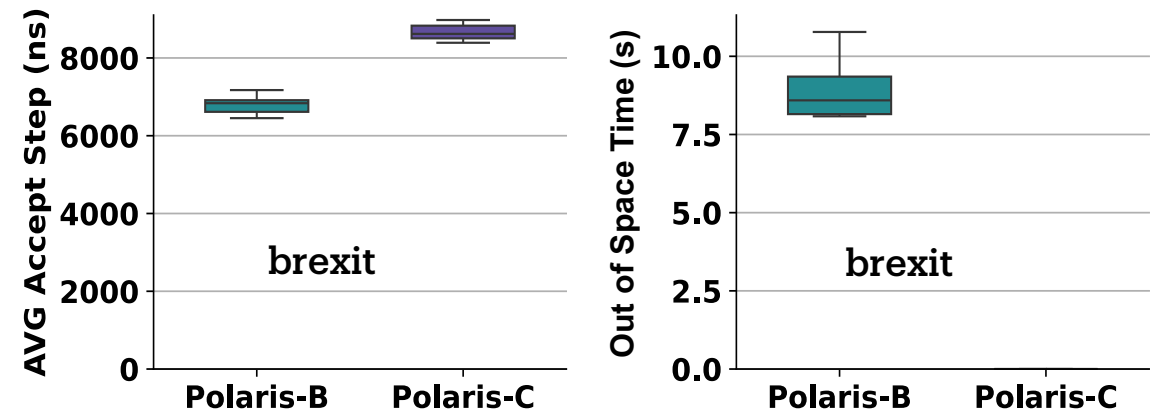
Comparison with Polaris-B



Larger numbers of colors can lead to more Out of Space operations

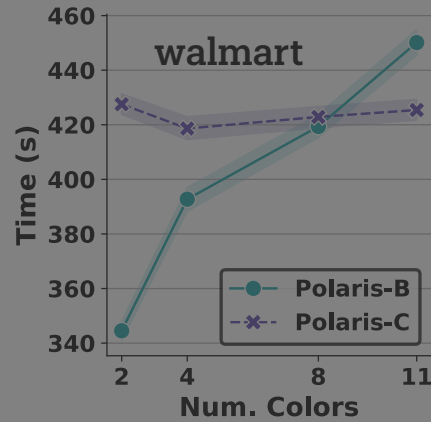
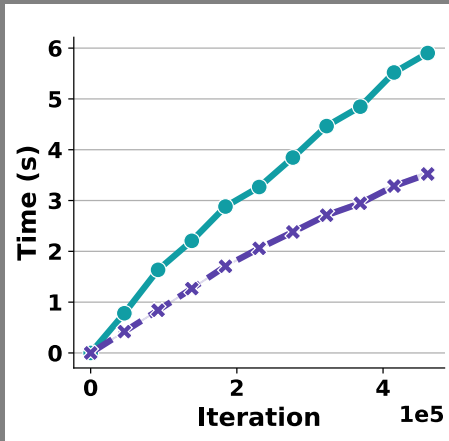


Polaris-B frequently performs self-loops

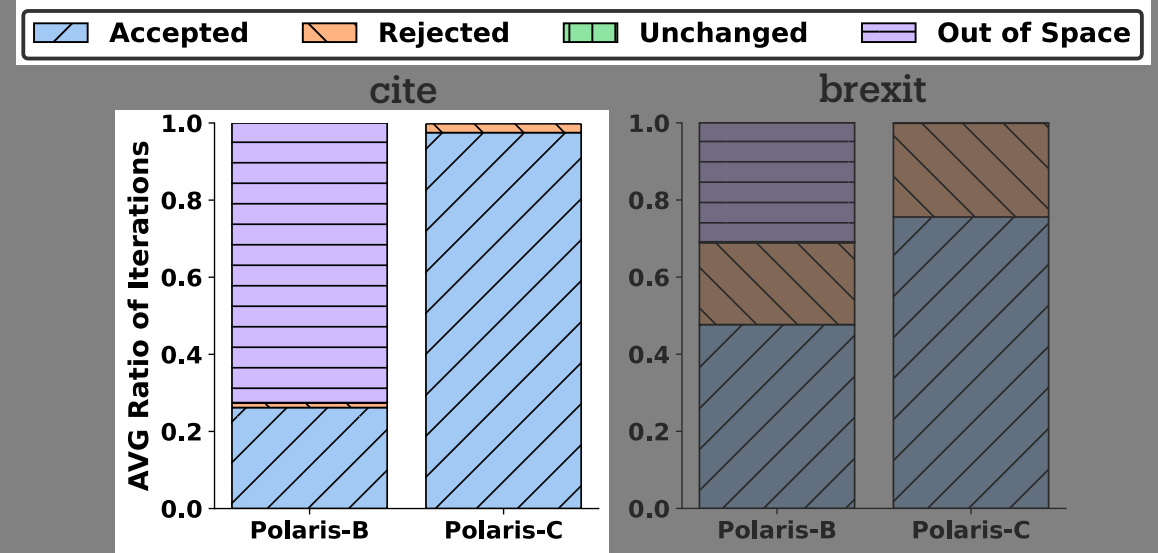


Polaris-B wastes time in Out Of Spate operations

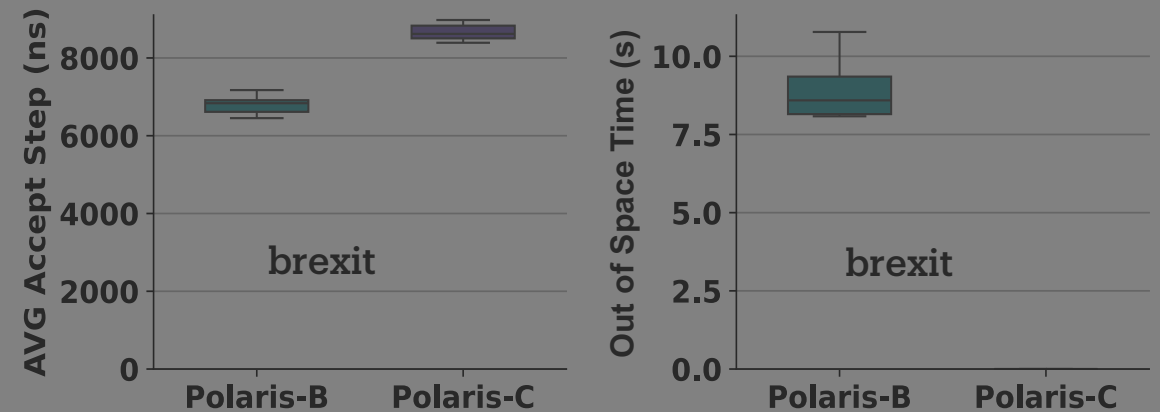
Comparison with Polaris-B



Larger numbers of colors can lead to more Out of Space operations

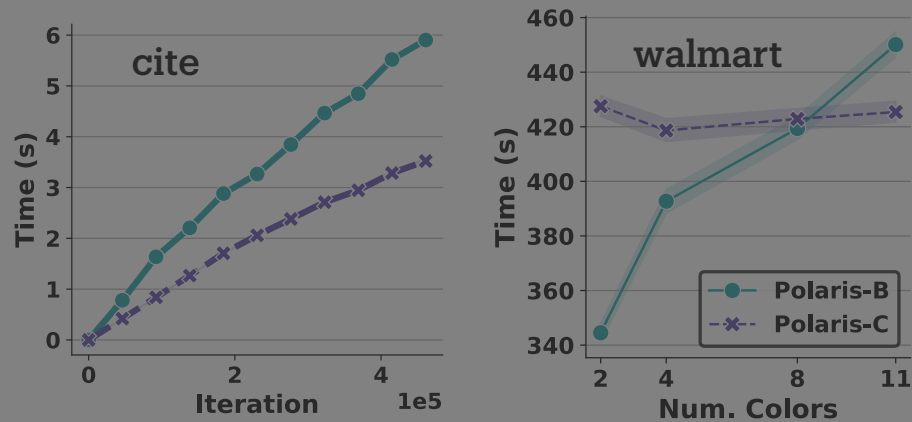


Polaris-B frequently performs self-loops

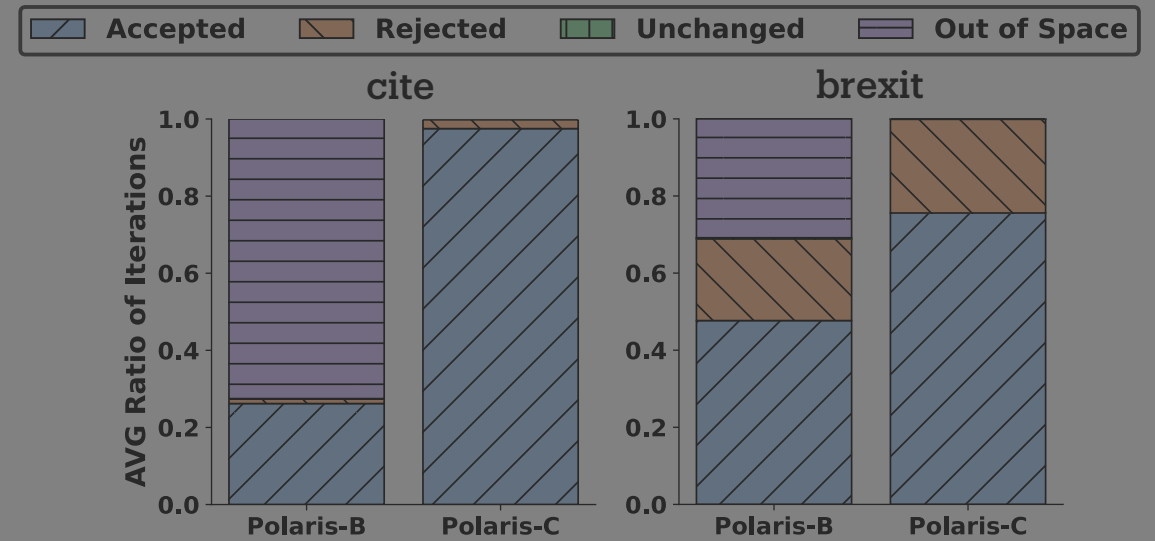


Polaris-B wastes time in Out Of Spate operations

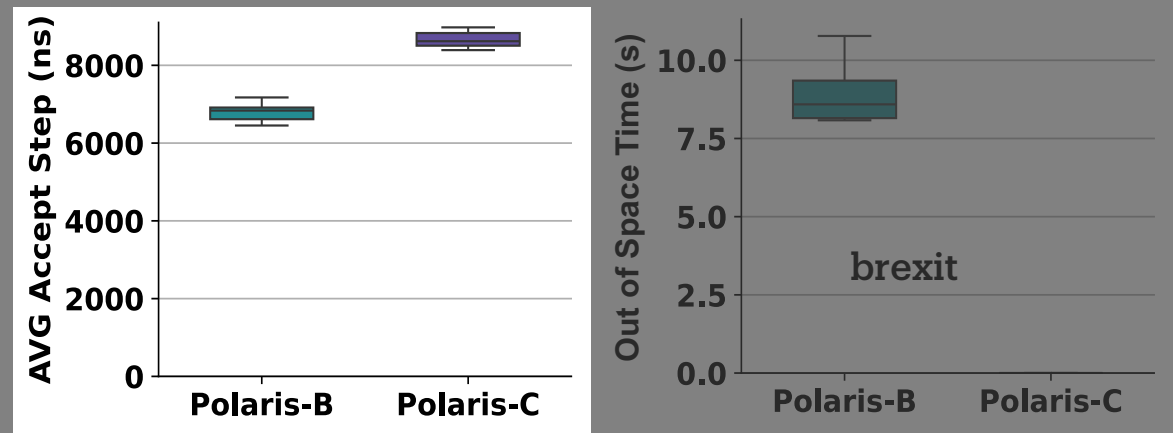
Comparison with Polaris-B



Larger numbers of colors can lead to more Out of Space operations

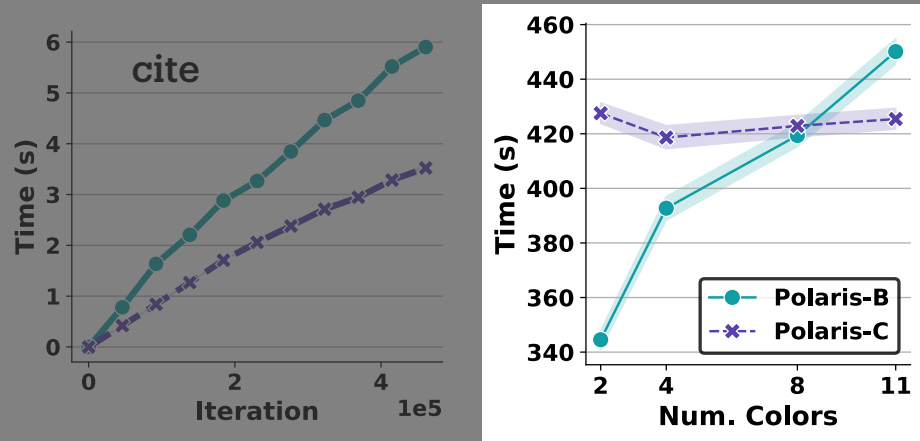


Polaris-B frequently performs self-loops

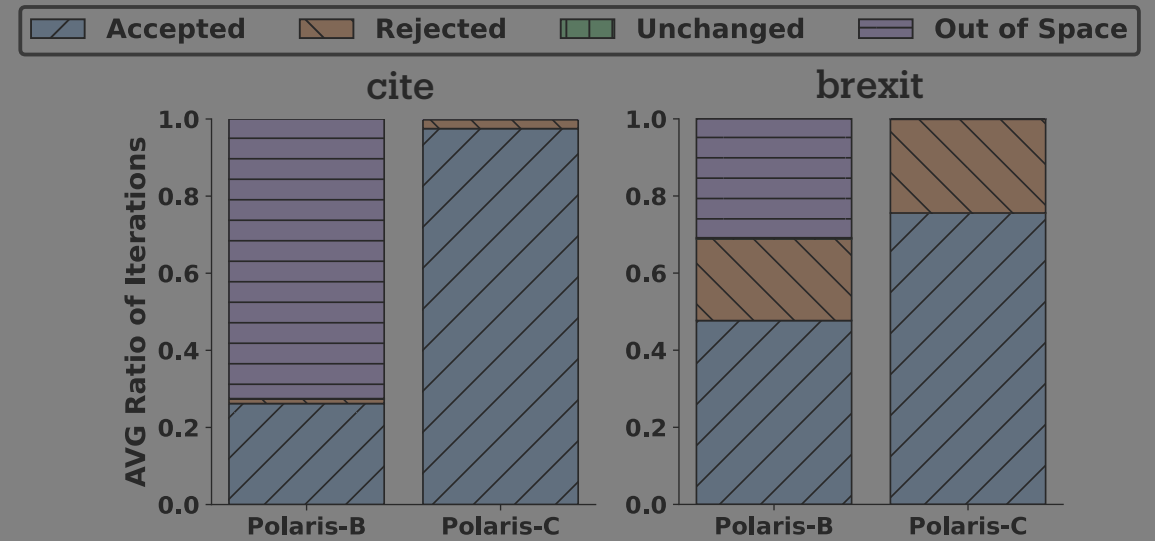


Polaris-B wastes time in Out Of Spate operations

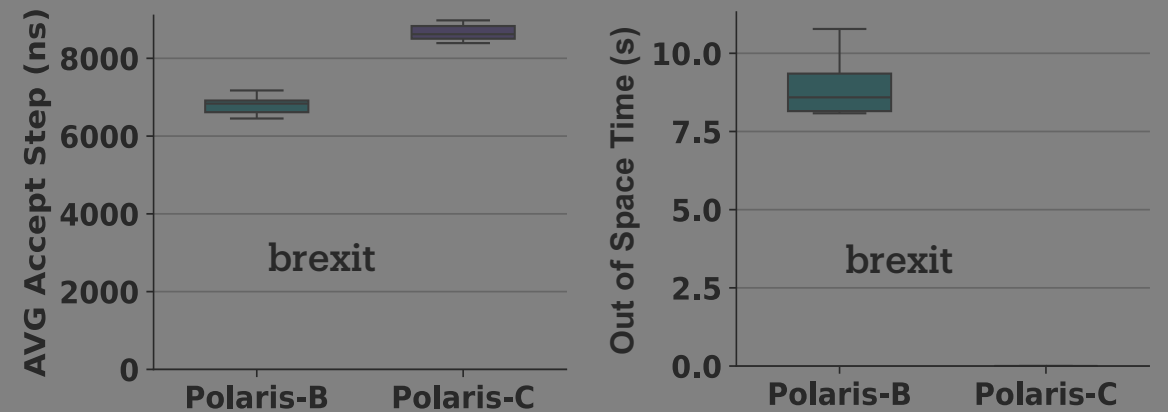
Comparison with Polaris-B



Larger numbers of colors can lead to more Out of Space operations



Polaris-B frequently performs self-loops



Polaris-B wastes time in Out Of Spate operations

POLARIS

Sampling from the Multigraph Configuration
Model with Prescribed Color Assortativity

Giulia
Preti

giulia.preti@centai.eu



Conclusions

- We introduced the micro-canonical ensemble of colored multigraphs with prescribed JCM
- We described two MCMC-MH sampling algorithms
- We showed the shortcomings of the CM in capturing the color assortativity
- We showed the advantages of the color-aware algorithm over the baseline
- Future works include the analysis of polarization in real networks